

D1Q3 ADE,

a supplementary material for

Lattice Boltzmann Method Analysis Tool (LBMAT)

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1 Global definitions

In \mathbb{R}^1 , the position and velocity vectors are given by $\mathbf{x} = (x_1)$ and $\mathbf{v} = (v_1)$, respectively.

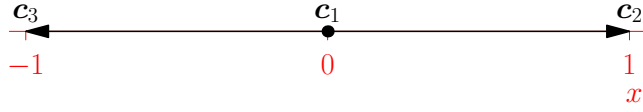
1.1 Discrete velocity vectors

Discrete velocity vectors and the lattice speed of sound are defined by

$$\{\mathbf{c}_i\}_{i=1}^3 = ((0), (1), (-1)),$$

$$c_s = \frac{1}{\sqrt{3}},$$

respectively [1].



1.2 Raw and central moments

The raw and central moments are defined by

$$m_{\alpha} := \sum_{i=1}^3 f_i c_i^{\alpha},$$

and

$$k_{\alpha} := \sum_{i=1}^3 f_i (c_i - v)^{\alpha},$$

respectively, where $\alpha = (\alpha_1) \in \mathbb{Z}^1$ denotes a multi-index and $c_i^{\alpha} := [c_i]_1^{\alpha_1}$.

1.3 Transformation matrix \mathbf{M}

Matrix \mathbf{M} , that defines macroscopic quantities (moments) $\boldsymbol{\mu}$ by

$$\boldsymbol{\mu} = \mathbf{M}\mathbf{f},$$

with $\mathbf{f} = (f_1, f_2, f_3)^T$, is selected such that

$$\boldsymbol{\mu} = \left(m_{(0)}, m_{(1)}, m_{(2)} \right)^T,$$

i.e., \mathbf{M} is given by

$$\mathbf{M} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{pmatrix}.$$

1.4 Equilibrium

The corresponding equilibrium raw moments are defined using the continuous Maxwell–Boltzmann distribution function [1]

$$f^{(eq)}(\xi) = \frac{\rho}{(2\pi c_s^2)^{\frac{1}{2}}} \exp\left(-\frac{(\xi - v_1)^2}{2c_s^2}\right)$$

as

$$m_{(\alpha)}^{(eq)} = \int_{\mathbb{R}} \xi^\alpha f^{(eq)}(\xi) d\xi,$$

where $\alpha \in \{0, 1, 2\}$. Hence, the equilibrium moments $\boldsymbol{\mu}^{(eq)}$ satisfy

$$\boldsymbol{\mu}^{(eq)} = \left(\rho, \rho v_1, \rho(v_1^2 + c_s^2)\right)^T.$$

2 Spatial EPDEs

2.1 SRT

2.1.1 Definitions

Collision operator C :

$$C(\mathbf{f}) = \omega \left(\mathbf{M}^{-1} \boldsymbol{\mu}^{(eq)} - \mathbf{f} \right),$$

$\omega \in (0, 2)$.

2.1.2 Conservation of mass equation

$$\begin{aligned} & \frac{\partial \rho}{\partial t} + \frac{\delta_l v_1}{\delta_t} \frac{\partial \rho}{\partial x_1} + \frac{\rho \delta_l}{\delta_t} \frac{\partial v_1}{\partial x_1} + (-2 + \omega) \frac{\delta_l}{2\omega} \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial t} + (-2 + \omega) \frac{\delta_l^2 v_1}{2\omega \delta_t} \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial x_1} + (-2 + \omega) \frac{\rho \delta_l^2}{2\omega \delta_t} \left(\frac{\partial v_1}{\partial x_1} \right)^2 + \\ & (-2 + \omega) \frac{\rho \delta_l}{2\omega} \frac{\partial^2 v_1}{\partial t \partial x_1} + (-2 + \omega) \frac{c_s^2 \delta_l^2}{2\omega \delta_t} \frac{\partial^2 \rho}{\partial x_1^2} + (-2 + \omega) \frac{\rho \delta_l^2 v_1}{2\omega \delta_t} \frac{\partial^2 v_1}{\partial x_1^2} + (12 - 12\omega + \omega^2) \frac{\rho \delta_l \delta_t}{12\omega^2} \frac{\partial^3 v_1}{\partial t^2 \partial x_1} + \\ & (12 - 12\omega + \omega^2) \frac{\rho \delta_l^2 v_1}{6\omega^2} \frac{\partial^3 v_1}{\partial t \partial x_1^2} + (6 - 18c_s^2 - 6\omega + 6\omega v_1^2 - \omega^2 v_1^2 + 18c_s^2 \omega - 6v_1^2 + \omega^2 - 3c_s^2 \omega^2) \frac{\delta_l^3 v_1}{6\omega^2 \delta_t} \frac{\partial^3 \rho}{\partial x_1^3} + \\ & (12 - 24c_s^2 - 12\omega + 24\omega v_1^2 - 5\omega^2 v_1^2 + 24c_s^2 \omega - 24v_1^2 + 2\omega^2 - 3c_s^2 \omega^2) \frac{\rho \delta_l^3}{12\omega^2 \delta_t} \frac{\partial^3 v_1}{\partial x_1^3} + (-2 + 3\omega - \omega^2) \frac{\rho \delta_l \delta_t^2}{2\omega^3} \frac{\partial^4 v_1}{\partial t^3 \partial x_1} + \\ & (-2 + 3\omega - \omega^2) \frac{3\rho \delta_l^2 v_1 \delta_t}{2\omega^3} \frac{\partial^4 v_1}{\partial t^2 \partial x_1^2} + C_1 \frac{\rho \delta_l^3}{12\omega^3} \frac{\partial^4 v_1}{\partial t \partial x_1^3} + C_2 \frac{\delta_l^4}{24\omega^3 \delta_t} \frac{\partial^4 \rho}{\partial x_1^4} + C_3 \frac{\rho \delta_l^4 v_1}{12\omega^3 \delta_t} \frac{\partial^4 v_1}{\partial x_1^4} = 0, \end{aligned}$$

where:

$$\begin{aligned} C_1 &= -36 + 60c_s^2 + 54\omega - 108\omega v_1^2 + 42\omega^2 v_1^2 + \omega^3 - 90c_s^2 \omega + 72v_1^2 - 20\omega^2 - 2c_s^2 \omega^3 - 3\omega^3 v_1^2 + 34c_s^2 \omega^2 \\ C_2 &= -84c_s^2 \omega^2 v_1^2 - 24c_s^2 + 3\omega^3 v_1^4 - 72c_s^4 \omega + 30c_s^4 \omega^2 - 42\omega^2 v_1^4 + 6c_s^2 \omega^3 v_1^2 - 3c_s^4 \omega^3 - 108\omega v_1^2 - 72v_1^4 + 42\omega^2 v_1^2 + 36c_s^2 \omega + 72v_1^2 + 108\omega v_1^4 + \\ & c_s^2 \omega^3 + 48c_s^4 - 3\omega^3 v_1^2 + 216c_s^2 \omega v_1^2 - 14c_s^2 \omega^2 - 144c_s^2 v_1^2 \\ C_3 &= 24 - 48c_s^2 - 36\omega + 54\omega v_1^2 - 22\omega^2 v_1^2 - \omega^3 + 72c_s^2 \omega - 36v_1^2 + 14\omega^2 + c_s^2 \omega^3 + 2\omega^3 v_1^2 - 26c_s^2 \omega^2 \end{aligned}$$

2.2 MRT

2.2.1 Definitions

Collision operator \mathbf{C} :

$$\mathbf{C}(\mathbf{f}) = \mathbf{M}^{-1} \mathbf{S} \left(\boldsymbol{\mu}^{(eq)} - \mathbf{M} \mathbf{f} \right),$$

where

$$\mathbf{S} = \text{diag}(\omega_1, \omega_2, \omega_3),$$

$$\omega_1, \omega_2, \omega_3 \in (0, 2).$$

2.2.2 Conservation of mass equation

$$\begin{aligned} & \frac{\partial \rho}{\partial t} + \frac{v_1 \delta_l}{\delta_t} \frac{\partial \rho}{\partial x_1} + \frac{\rho \delta_l}{\delta_t} \frac{\partial v_1}{\partial x_1} + (-2 + \omega_2) \frac{\delta_l}{2\omega_2} \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial t} + (-2 + \omega_2) \frac{v_1 \delta_l^2}{2\delta_t \omega_2} \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial x_1} + (-2 + \omega_2) \frac{\rho \delta_l^2}{2\delta_t \omega_2} \left(\frac{\partial v_1}{\partial x_1} \right)^2 + \\ & (-2 + \omega_2) \frac{\rho \delta_l}{2\omega_2} \frac{\partial^2 v_1}{\partial t \partial x_1} + (-2 + \omega_2) \frac{c_s^2 \delta_l^2}{2\delta_t \omega_2} \frac{\partial^2 \rho}{\partial x_1^2} + (-2 + \omega_2) \frac{v_1 \rho \delta_l^2}{2\delta_t \omega_2} \frac{\partial^2 v_1}{\partial x_1^2} + (12 + \omega_2^2 - 12\omega_2) \frac{\delta_t \rho \delta_l}{12\omega_2^2} \frac{\partial^3 v_1}{\partial t^2 \partial x_1} + \\ & (12 - 6\omega_3 + \omega_3 \omega_2 - 6\omega_2) \frac{v_1 \rho \delta_l^2}{6\omega_3 \omega_2} \frac{\partial^3 v_1}{\partial t \partial x_1^2} + C_1 \frac{v_1 \delta_l^3}{6\omega_3 \delta_t \omega_2^2} \frac{\partial^3 \rho}{\partial x_1^3} + C_2 \frac{\rho \delta_l^3}{12\omega_3 \delta_t \omega_2^2} \frac{\partial^3 v_1}{\partial x_1^3} + (-2 - \omega_2^2 + 3\omega_2) \frac{\delta_t^2 \rho \delta_l}{2\omega_2^3} \frac{\partial^4 v_1}{\partial t^3 \partial x_1} + \\ & (-\omega_3^2 \omega_2^2 - \omega_3^2 \omega_2 - 4\omega_2^2 - 4\omega_3 \omega_2 + 2\omega_2^3 - 2\omega_3 \omega_2^2 + 8\omega_3 \omega_2^2 + 2\omega_3^2) \frac{\delta_t v_1 \rho \delta_l^2}{2\omega_3 \omega_2^3} \frac{\partial^4 v_1}{\partial t^2 \partial x_1^2} + C_3 \frac{\rho \delta_l^3}{12\omega_3 \omega_2^3} \frac{\partial^4 v_1}{\partial t \partial x_1^3} + \\ & C_4 \frac{\delta_l^4}{24\omega_3^2 \delta_t \omega_2^3} \frac{\partial^4 \rho}{\partial x_1^4} + C_5 \frac{v_1 \rho \delta_l^4}{12\omega_3^2 \delta_t \omega_2^3} \frac{\partial^4 v_1}{\partial x_1^4} = 0, \end{aligned}$$

where:

$$\begin{aligned} C_1 &= 15\omega_3 c_s^2 \omega_2 - 6c_s^2 \omega_2 + 3v_1^2 \omega_2^2 - \omega_3 v_1^2 \omega_2^2 - 12\omega_3 c_s^2 - 6v_1^2 \omega_2 + 3\omega_3 v_1^2 \omega_2 - 3\omega_3 c_s^2 \omega_2^2 + 3c_s^2 \omega_2^2 - 3\omega_2^2 - 3\omega_3 \omega_2 + 6\omega_2 + \omega_3 \omega_2^2 \\ C_2 &= 18\omega_3 c_s^2 \omega_2 - 12\omega_3 v_1^2 - 12c_s^2 \omega_2 + 6v_1^2 \omega_2^2 - 5\omega_3 v_1^2 \omega_2^2 - 12\omega_3 c_s^2 - 12v_1^2 \omega_2 + 18\omega_3 v_1^2 \omega_2 - 3\omega_3 c_s^2 \omega_2^2 + 6c_s^2 \omega_2^2 - 6\omega_2^2 - 6\omega_3 \omega_2 + 12\omega_2 + 2\omega_3 \omega_2^2 \\ C_3 &= 24\omega_3 c_s^2 \omega_2 + 15\omega_3 v_1^2 \omega_2^3 - 6v_1^2 \omega_2^3 - 11\omega_3^2 \omega_2^2 + \omega_3^2 \omega_2^3 + 12v_1^2 \omega_2^2 - 60\omega_3 v_1^2 \omega_2^2 - 6c_s^2 \omega_2^3 + 48\omega_3 v_1^2 \omega_2 + 9\omega_3 c_s^2 \omega_2^3 - 36\omega_3 c_s^2 \omega_2^2 + 12\omega_3^2 \omega_2 + 12c_s^2 \omega_2^2 - 12\omega_2^2 - 2\omega_3^2 c_s^2 \omega_2^3 - 42\omega_3^2 v_1^2 \omega_2 - 24\omega_3 \omega_2 + 6\omega_2^3 + 25\omega_3^2 c_s^2 \omega_2^2 - 9\omega_3 \omega_2^3 - 3\omega_3^2 v_1^2 \omega_2^3 + 24\omega_3^2 c_s^2 - 48\omega_3^2 c_s^2 \omega_2 + 12\omega_3^2 v_1^2 + 27\omega_3^2 v_1^2 \omega_2^2 + 36\omega_3 \omega_2^2 \\ C_4 &= -24\omega_3 c_s^2 \omega_2 + 18\omega_3 v_1^2 \omega_2^3 - 12v_1^2 \omega_2^3 + 24\omega_3^2 c_s^4 + 156\omega_3^2 v_1^2 c_s^2 \omega_2 + 24\omega_3^2 c_s^4 \omega_2^2 - 96\omega_3^2 v_1^2 c_s^2 + 24v_1^2 \omega_2^2 - 72\omega_3 v_1^2 \omega_2^2 - 3\omega_3^2 c_s^4 \omega_2^3 + 24\omega_3^2 v_1^4 \omega_2 + 6\omega_3^2 v_1^2 c_s^2 \omega_2^3 - 24\omega_3^2 v_1^4 \omega_2^2 + 48\omega_3 v_1^2 \omega_2 - 6\omega_3 c_s^2 \omega_2^3 - 72\omega_3^2 v_1^2 c_s^2 \omega_2^2 + 3\omega_3^2 v_1^4 \omega_2^3 - 48\omega_3^2 c_s^4 \omega_2 + 24\omega_3 c_s^2 \omega_2^2 - 24\omega_3 v_1^2 c_s^2 \omega_2 - 24v_1^4 \omega_2^2 + 72\omega_3 v_1^4 \omega_2^2 + \omega_3^2 c_s^2 \omega_2^3 - 24\omega_3^2 v_1^2 \omega_2 + 24\omega_3 c_s^4 \omega_2 - 18\omega_3 v_1^4 \omega_2^3 + 12v_1^4 \omega_2^3 - 8\omega_3^2 c_s^2 \omega_2^2 + 12v_1^2 c_s^2 \omega_2^3 - 3\omega_3^2 v_1^2 \omega_2^3 + 12\omega_3^2 c_s^2 \omega_2 - 24\omega_3 c_s^4 \omega_2^2 - 12\omega_3 v_1^2 c_s^2 \omega_2^3 + 24\omega_3^2 v_1^2 \omega_2^2 - 24v_1^2 c_s^2 \omega_2^2 + 48\omega_3 v_1^2 c_s^2 \omega_2^2 - 48\omega_3 v_1^4 \omega_2 + 6\omega_3 c_s^4 \omega_2^3 \\ C_5 &= -12\omega_3 c_s^2 \omega_2 - 6\omega_3 v_1^2 \omega_2^3 + 6v_1^2 \omega_2^3 + 8\omega_3^2 \omega_2^2 - \omega_3^2 \omega_2^3 - 12v_1^2 \omega_2^2 + 24\omega_3 v_1^2 \omega_2^2 + 6c_s^2 \omega_2^3 - 12\omega_3 v_1^2 \omega_2 - 6\omega_3 c_s^2 \omega_2^3 + 24\omega_3 c_s^2 \omega_2^2 - 6\omega_3^2 \omega_2 - 12c_s^2 \omega_2^2 + 12\omega_2^2 + \omega_3^2 c_s^2 \omega_2^3 + 24\omega_3^2 v_1^2 \omega_2 + 12\omega_3 \omega_2 - 6\omega_2^3 - 20\omega_3^2 c_s^2 \omega_2^2 + 6\omega_3 \omega_2^3 + 2\omega_3^2 v_1^2 \omega_2^3 - 24\omega_3^2 c_s^2 + 42\omega_3^2 c_s^2 \omega_2 - 12\omega_3^2 v_1^2 - 16\omega_3^2 v_1^2 \omega_2^2 - 24\omega_3 \omega_2^2 \end{aligned}$$

2.3 CLBM

2.3.1 Definitions

Collision operator \mathbf{C} :

$$\mathbf{C}(\mathbf{f}) = \mathbf{K}^{-1} \mathbf{S} \left(\boldsymbol{\kappa}^{(eq)} - \mathbf{K} \mathbf{f} \right),$$

where

$$\mathbf{S} = \text{diag}(\omega_1, \omega_2, \omega_3),$$

$$\omega_1, \omega_2, \omega_3 \in (0, 2).$$

Matrix \mathbf{K} corresponds to the transformation matrix to the central moment basis defined by

$$\boldsymbol{\kappa} = \left(k_{(0)}, k_{(1)}, k_{(2)} \right)^T$$

and is given by

$$\mathbf{K} = \begin{pmatrix} 1 & 1 & 1 \\ -v_1 & 1-v_1 & -v_1-1 \\ v_1^2 & (1-v_1)^2 & (v_1+1)^2 \end{pmatrix}.$$

The equilibrium central moments are defined by

$$\kappa^{(eq)} = \mathbf{K} \mathbf{M}^{-1} \boldsymbol{\mu}^{(eq)},$$

i.e.,

$$\kappa^{(eq)} = \left(\rho, 0, \rho c_s^2 \right)^T.$$

2.3.2 Conservation of mass equation

$$\begin{aligned} & \frac{\partial \rho}{\partial t} + \frac{\delta_l v_1}{\delta_t} \frac{\partial \rho}{\partial x_1} + \frac{\rho \delta_l}{\delta_t} \frac{\partial v_1}{\partial x_1} + (-2 + \omega_2) \frac{\delta_l}{2\omega_2} \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial t} + (-2 + \omega_2) \frac{\delta_l^2 v_1}{2\omega_2 \delta_t} \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial x_1} + (-2 + \omega_2) \frac{\rho \delta_l^2}{2\omega_2 \delta_t} \left(\frac{\partial v_1}{\partial x_1} \right)^2 + \\ & (-2 + \omega_2) \frac{\rho \delta_l}{2\omega_2} \frac{\partial^2 v_1}{\partial t \partial x_1} + (-2 + \omega_2) \frac{\delta_l^2 c_s^2}{2\omega_2 \delta_t} \frac{\partial^2 \rho}{\partial x_1^2} + (-2 + \omega_2) \frac{\rho \delta_l^2 v_1}{2\omega_2 \delta_t} \frac{\partial^2 v_1}{\partial x_1^2} + (12 - 12\omega_2 + \omega_2^2) \frac{\rho \delta_l \delta_t}{12\omega_2^2} \frac{\partial^3 v_1}{\partial t^2 \partial x_1} + \\ & (12 - 12\omega_2 + \omega_2^2) \frac{\rho \delta_l^2 v_1}{6\omega_2^2} \frac{\partial^3 v_1}{\partial t \partial x_1^2} + C_1 \frac{\delta_l^3 v_1}{6\omega_2 \omega_3 \delta_t} \frac{\partial^3 \rho}{\partial x_1^3} + C_2 \frac{\rho \delta_l^3}{12\omega_2^2 \omega_3 \delta_t} \frac{\partial^3 v_1}{\partial x_1^3} + (-2 + 3\omega_2 - \omega_2^2) \frac{\rho \delta_l \delta_t^2}{2\omega_2^2} \frac{\partial^4 v_1}{\partial t^3 \partial x_1} + \\ & (-2 + 3\omega_2 - \omega_2^2) \frac{3\rho \delta_l^2 \delta_t v_1}{2\omega_2^2} \frac{\partial^4 v_1}{\partial t^2 \partial x_1^2} + C_3 \frac{\rho \delta_l^3}{12\omega_2^3 \omega_3^2} \frac{\partial^4 v_1}{\partial t \partial x_1^3} + C_4 \frac{\delta_l^4}{24\omega_2^3 \omega_3^2 \delta_t} \frac{\partial^4 \rho}{\partial x_1^4} + C_5 \frac{\rho \delta_l^4 v_1}{12\omega_2^3 \omega_3^2 \delta_t} \frac{\partial^4 v_1}{\partial x_1^4} = 0, \end{aligned}$$

where:

$$\begin{aligned} C_1 &= 6 - 6v_1^2 - 3\omega_2 - 18c_s^2 + 3\omega_3 v_1^2 + 9\omega_3 c_s^2 - 3\omega_3 + 3\omega_2 v_1^2 + \omega_2 \omega_3 + 9\omega_2 c_s^2 - 3\omega_2 \omega_3 c_s^2 - \omega_2 \omega_3 v_1^2 \\ C_2 &= -3\omega_2^2 \omega_3 c_s^2 + 12\omega_2 - 5\omega_2^2 \omega_3 v_1^2 + 12\omega_3 v_1^2 + 6\omega_2^2 c_s^2 + 18\omega_2^2 v_1^2 - 12\omega_3 c_s^2 + 2\omega_2^2 \omega_3 - 36\omega_2 v_1^2 - 6\omega_2 \omega_3 - 6\omega_2^2 - 12\omega_2 c_s^2 + 18\omega_2 \omega_3 c_s^2 + 6\omega_2 \omega_3 v_1^2 \\ C_3 &= -36\omega_2^2 \omega_3 c_s^2 + 18\omega_2 \omega_3^2 v_1^2 - 6\omega_2^2 c_s^2 - 11\omega_2^2 \omega_3^2 - 108\omega_2^2 \omega_3 v_1^2 - 48\omega_2^2 \omega_3^2 c_s^2 - 9\omega_3^2 \omega_3 - 18\omega_2^2 v_1^2 + \omega_3^2 \omega_3^2 + 12\omega_2^2 c_s^2 - 2\omega_3^2 \omega_3^2 c_s^2 + 36\omega_2^2 v_1^2 + 36\omega_2^2 \omega_3 - 3\omega_2^2 \omega_3^2 v_1^2 + 24\omega_3^2 c_s^2 - 24\omega_2 \omega_3 - 12\omega_2^2 + 27\omega_3^2 \omega_3 v_1^2 - 36\omega_3^2 v_1^2 + 9\omega_3^2 \omega_3 c_s^2 + 6\omega_2^2 + 15\omega_2^2 \omega_3^2 v_1^2 + 24\omega_2 \omega_3 c_s^2 + 25\omega_2^2 \omega_3^2 c_s^2 + 72\omega_2 \omega_3 v_1^2 + 12\omega_2 \omega_3^2 \\ C_4 &= 24\omega_2^2 \omega_3 c_s^2 - 12\omega_2^2 \omega_3^2 v_1^4 + 24\omega_2 \omega_3 c_s^4 - 72\omega_2^2 \omega_3 v_1^2 + 12\omega_2 \omega_3^2 c_s^2 + 24\omega_2^2 \omega_3^2 c_s^4 - 36\omega_2^2 v_1^2 - 12\omega_2^2 \omega_3^2 c_s^2 v_1^2 - 30\omega_2^2 \omega_3 v_1^4 + 6\omega_2^2 \omega_3^2 c_s^2 v_1^2 + 24\omega_3^2 c_s^4 + \omega_3^2 \omega_3^2 c_s^2 + 72\omega_2^2 v_1^2 + 6\omega_3^2 \omega_3 c_s^4 + 72\omega_2 \omega_3 c_s^2 v_1^2 - 3\omega_3^2 \omega_3^2 v_1^2 - 216\omega_2^2 c_s^2 v_1^2 - 3\omega_3^2 \omega_3^2 c_s^4 + 30\omega_3^2 \omega_3 v_1^2 - 72\omega_3^2 \omega_3 c_s^2 v_1^2 + 3\omega_3^2 \omega_3^2 v_1^4 - 36\omega_2 \omega_3^2 c_s^2 v_1^2 - 6\omega_2^2 \omega_3^2 c_s^2 - 72\omega_2^2 v_1^4 + 108\omega_3^2 c_s^2 v_1^2 + 12\omega_2^2 \omega_3^2 v_1^2 - 24\omega_2 \omega_3 c_s^2 - 24\omega_2^2 \omega_3 c_s^4 - 8\omega_2^2 \omega_3^2 c_s^2 + 36\omega_2^2 v_1^4 + 72\omega_2^2 \omega_3 v_1^4 + 144\omega_2^2 \omega_3 c_s^2 v_1^2 - 48\omega_2 \omega_3^2 c_s^4 \\ C_5 &= 72\omega_2^2 \omega_3 c_s^2 - 12\omega_2^2 \omega_3^2 v_1^2 + 30\omega_3^2 c_s^2 + 2\omega_2^2 \omega_3^2 + 24\omega_2^2 \omega_3 v_1^2 - 30\omega_2 \omega_3^2 c_s^2 + 12\omega_3^2 \omega_3 + 42\omega_3^2 v_1^2 - \omega_2^2 \omega_3^2 - 60\omega_2^2 c_s^2 + \omega_3^2 \omega_3^2 c_s^2 - 84\omega_2^2 v_1^2 - 24\omega_2^2 \omega_3 + 2\omega_2^2 \omega_3^2 v_1^2 + 24\omega_3^2 c_s^2 - 12\omega_2 \omega_3 + 36\omega_2^2 - 24\omega_3^2 \omega_3 v_1^2 - 12\omega_3^2 v_1^2 - 24\omega_3^2 \omega_3 c_s^2 - 18\omega_3^2 + 2\omega_2^2 \omega_3^2 v_1^2 - 12\omega_2 \omega_3 c_s^2 - 2\omega_2^2 \omega_3^2 c_s^2 + 60\omega_2 \omega_3 v_1^2 + 6\omega_2 \omega_3^2 \end{aligned}$$

3 Comparison of SRT, MRT, and CLBM

3.1 Conservation of mass equation

$$\begin{aligned} & \frac{\partial \rho}{\partial t} + v_1 \frac{\delta_l}{\delta_t} \frac{\partial \rho}{\partial x_1} + \rho \frac{\delta_l}{\delta_t} \frac{\partial v_1}{\partial x_1} + C_{D_x \rho, D_t v_1}^{(0)} \delta_l \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial t} + C_{D_x \rho, D_x v_1}^{(0)} \frac{\delta_l^2}{\delta_t} \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial x_1} + C_{D_x v_1, D_x v_1}^{(0)} \frac{\delta_l^2}{\delta_t} \left(\frac{\partial v_1}{\partial x_1} \right)^2 + \\ & C_{D_t D_x v_1}^{(0)} \delta_l \frac{\partial^2 v_1}{\partial t \partial x_1} + C_{D_x^2 \rho}^{(0)} \frac{\delta_l^2}{\delta_t} \frac{\partial^2 \rho}{\partial x_1^2} + C_{D_x^2 v_1}^{(0)} \frac{\delta_l^2}{\delta_t} \frac{\partial^2 v_1}{\partial x_1^2} + C_{D_t^2 D_x v_1}^{(0)} \delta_l \delta_t \frac{\partial^3 v_1}{\partial t^2 \partial x_1} + C_{D_t D_x^2 v_1}^{(0)} \delta_l^2 \frac{\partial^3 v_1}{\partial t \partial x_1^2} + C_{D_x^3 \rho}^{(0)} \frac{\delta_l^3}{\delta_t} \frac{\partial^3 \rho}{\partial x_1^3} + \\ & C_{D_x^3 v_1}^{(0)} \frac{\delta_l^3}{\delta_t} \frac{\partial^3 v_1}{\partial x_1^3} + C_{D_t^3 D_x v_1}^{(0)} \delta_l \delta_t^2 \frac{\partial^4 v_1}{\partial t^3 \partial x_1} + C_{D_t^2 D_x^2 v_1}^{(0)} \delta_l^2 \delta_t \frac{\partial^4 v_1}{\partial t^2 \partial x_1^2} + C_{D_t D_x^3 v_1}^{(0)} \delta_l^3 \frac{\partial^4 v_1}{\partial t \partial x_1^3} + C_{D_x^4 \rho}^{(0)} \frac{\delta_l^4}{\delta_t} \frac{\partial^4 \rho}{\partial x_1^4} + C_{D_x^4 v_1}^{(0)} \frac{\delta_l^4}{\delta_t} \frac{\partial^4 v_1}{\partial x_1^4} \\ & = 0, \end{aligned}$$

where:

$$\text{coefficient } C_{D_x \rho, D_t v_1}^{(0)} \text{ at } \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial t} :$$

$$C_{D_x \rho, D_t v_1}^{(0), \text{SRT}} = (-2 + \omega) \frac{1}{2\omega}$$

$$C_{D_x \rho, D_t v_1}^{(0), \text{MRT1}} = (-2 + \omega_2) \frac{1}{2\omega_2}$$

$$C_{D_x \rho, D_t v_1}^{(0), \text{CLBM1}} = C_{D_x \rho, D_t v_1}^{(0), \text{MRT1}}$$

$$\text{coefficient } C_{D_x \rho, D_x v_1}^{(0)} \text{ at } \frac{\partial \rho}{\partial x_1} \frac{\partial v_1}{\partial x_1} :$$

$$C_{D_x \rho, D_x v_1}^{(0), \text{SRT}} = (-2 + \omega) \frac{v_1}{2\omega}$$

$$C_{D_x \rho, D_x v_1}^{(0), \text{MRT1}} = (-2 + \omega_2) \frac{v_1}{2\omega_2}$$

$$C_{D_x \rho, D_x v_1}^{(0), \text{CLBM1}} = C_{D_x \rho, D_x v_1}^{(0), \text{MRT1}}$$

$$\text{coefficient } C_{D_x v_1, D_x v_1}^{(0)} \text{ at } \left(\frac{\partial v_1}{\partial x_1} \right)^2 :$$

$$C_{D_x v_1, D_x v_1}^{(0), \text{SRT}} = (-2 + \omega) \frac{\rho}{2\omega}$$

$$C_{D_x v_1, D_x v_1}^{(0), \text{MRT1}} = (-2 + \omega_2) \frac{\rho}{2\omega_2}$$

$$C_{D_x v_1, D_x v_1}^{(0), \text{CLBM1}} = C_{D_x v_1, D_x v_1}^{(0), \text{MRT1}}$$

$$\text{coefficient } C_{D_t D_x v_1}^{(0)} \text{ at } \frac{\partial^2 v_1}{\partial t \partial x_1} :$$

$$C_{D_t D_x v_1}^{(0), \text{SRT}} = (-2 + \omega) \frac{\rho}{2\omega}$$

$$C_{D_t D_x v_1}^{(0), \text{MRT1}} = (-2 + \omega_2) \frac{\rho}{2\omega_2}$$

$$C_{D_t D_x v_1}^{(0), \text{CLBM1}} = C_{D_t D_x v_1}^{(0), \text{MRT1}}$$

$$\text{coefficient } C_{D_x^2 \rho}^{(0)} \text{ at } \frac{\partial^2 \rho}{\partial x_1^2} :$$

$$C_{D_x^2 \rho}^{(0), \text{SRT}} = (-2 + \omega) \frac{c_s^2}{2\omega}$$

$$C_{D_x^2 \rho}^{(0), \text{MRT1}} = (-2 + \omega_2) \frac{c_s^2}{2\omega_2}$$

$$C_{D_x^2 \rho}^{(0), \text{CLBM1}} = C_{D_x^2 \rho}^{(0), \text{MRT1}}$$

$$\text{coefficient } C_{D_x^2 v_1}^{(0)} \text{ at } \frac{\partial^2 v_1}{\partial x_1^2} :$$

$$C_{D_x^2 v_1}^{(0), \text{SRT}} = (-2 + \omega) \frac{\rho v_1}{2\omega}$$

$$C_{D_x^2 v_1}^{(0), \text{MRT1}} = (-2 + \omega_2) \frac{\rho v_1}{2\omega_2}$$

$$C_{D_x^2 v_1}^{(0), \text{CLBM1}} = C_{D_x^2 v_1}^{(0), \text{MRT1}}$$

$$\text{coefficient } C_{D_t^2 D_x v_1}^{(0)} \text{ at } \frac{\partial^3 v_1}{\partial t^2 \partial x_1} :$$

$$C_{D_t^2 D_x v_1}^{(0), \text{SRT}} = (12 - 12\omega + \omega^2) \frac{\rho}{12\omega^2}$$

$$C_{D_t^2 D_x v_1}^{(0), \text{MRT1}} = (12 + \omega_2^2 - 12\omega_2) \frac{\rho}{12\omega_2^2}$$

$$C_{D_t^2 D_x v_1}^{(0), \text{CLBM1}} = C_{D_t^2 D_x v_1}^{(0), \text{MRT1}}$$

$$\text{coefficient } C_{D_t D_x^2 v_1}^{(0)} \text{ at } \frac{\partial^3 v_1}{\partial t \partial x_1^2} :$$

$$C_{D_t D_x^2 v_1}^{(0), \text{SRT}} = (12 - 12\omega + \omega^2) \frac{\rho v_1}{6\omega^2}$$

$$C_{D_t D_x^2 v_1}^{(0), \text{MRT}^1} = (12 - 6\omega_2 - 6\omega_3 + \omega_2 \omega_3) \frac{\rho v_1}{6\omega_2 \omega_3}$$

$$C_{D_t D_x^2 v_1}^{(0), \text{CLBM}^1} = (12 + \omega_2^2 - 12\omega_2) \frac{\rho v_1}{6\omega_2^2}$$

coefficient $C_{D_x^3 \rho}^{(0)}$ **at** $\frac{\partial^3 \rho}{\partial x_1^3}$:

$$C_{D_x^3 \rho}^{(0), \text{SRT}} = (6 - 6v_1^2 - 6\omega - 3\omega^2 c_s^2 + \omega^2 + 6\omega v_1^2 - \omega^2 v_1^2 - 18c_s^2 + 18\omega c_s^2) \frac{v_1}{6\omega^2}$$

$$C_{D_x^3 \rho}^{(0), \text{MRT}^1} = (\omega_2^2 \omega_3 + 3\omega_2^2 v_1^2 - 3\omega_2^2 - \omega_2^2 \omega_3 v_1^2 + 6\omega_2 - 6\omega_2 c_s^2 + 15\omega_2 \omega_3 c_s^2 - 12\omega_3 c_s^2 - 3\omega_2^2 \omega_3 c_s^2 + 3\omega_2^2 c_s^2 + 3\omega_2 \omega_3 v_1^2 - 6\omega_2 v_1^2 - 3\omega_2 \omega_3) \frac{v_1}{6\omega_2^2 \omega_3}$$

$$C_{D_x^3 \rho}^{(0), \text{CLBM}^1} = (6 - 6v_1^2 + 3\omega_3 v_1^2 - 3\omega_2 + 9\omega_2 c_s^2 - 3\omega_2 \omega_3 c_s^2 - 3\omega_3 + 9\omega_3 c_s^2 - 18c_s^2 - \omega_2 \omega_3 v_1^2 + 3\omega_2 v_1^2 + \omega_2 \omega_3) \frac{v_1}{6\omega_2 \omega_3}$$

coefficient $C_{D_x^3 v_1}^{(0)}$ **at** $\frac{\partial^3 v_1}{\partial x_1^3}$:

$$C_{D_x^3 v_1}^{(0), \text{SRT}} = (12 - 24v_1^2 - 12\omega - 3\omega^2 c_s^2 + 2\omega^2 + 24\omega v_1^2 - 5\omega^2 v_1^2 - 24c_s^2 + 24\omega c_s^2) \frac{\rho}{12\omega^2}$$

$$C_{D_x^3 v_1}^{(0), \text{MRT}^1} = (2\omega_2^2 \omega_3 + 6\omega_2^2 v_1^2 - 6\omega_2^2 - 5\omega_2^2 \omega_3 v_1^2 - 12\omega_3 v_1^2 + 12\omega_2 - 12\omega_2 c_s^2 + 18\omega_2 \omega_3 c_s^2 - 12\omega_3 c_s^2 - 3\omega_2^2 \omega_3 c_s^2 + 6\omega_2^2 c_s^2 + 18\omega_2 \omega_3 v_1^2 - 12\omega_2 v_1^2 - 6\omega_2 \omega_3) \frac{\rho}{12\omega_2^2 \omega_3}$$

$$C_{D_x^3 v_1}^{(0), \text{CLBM}^1} = (2\omega_2^2 \omega_3 + 18\omega_2^2 v_1^2 - 6\omega_2^2 - 5\omega_2^2 \omega_3 v_1^2 + 12\omega_3 v_1^2 + 12\omega_2 - 12\omega_2 c_s^2 + 18\omega_2 \omega_3 c_s^2 - 12\omega_3 c_s^2 - 3\omega_2^2 \omega_3 c_s^2 + 6\omega_2^2 c_s^2 + 6\omega_2 \omega_3 v_1^2 - 36\omega_2 v_1^2 - 6\omega_2 \omega_3) \frac{\rho}{12\omega_2^2 \omega_3}$$

coefficient $C_{D_t^3 D_x v_1}^{(0)}$ **at** $\frac{\partial^4 v_1}{\partial t^3 \partial x_1}$:

$$C_{D_t^3 D_x v_1}^{(0), \text{SRT}} = (-2 + 3\omega - \omega^2) \frac{\rho}{2\omega^3}$$

$$C_{D_t^3 D_x v_1}^{(0), \text{MRT}^1} = (-2 - \omega_2^2 + 3\omega_2) \frac{\rho}{2\omega_2^3}$$

$$C_{D_t^3 D_x v_1}^{(0), \text{CLBM}^1} = C_{D_t^3 D_x v_1}^{(0), \text{MRT}^1}$$

coefficient $C_{D_t^2 D_x^2 v_1}^{(0)}$ **at** $\frac{\partial^4 v_1}{\partial t^2 \partial x_1^2}$:

$$C_{D_t^2 D_x^2 v_1}^{(0), \text{SRT}} = (-2 + 3\omega - \omega^2) \frac{3\rho v_1}{2\omega^3}$$

$$C_{D_t^2 D_x^2 v_1}^{(0), \text{MRT}^1} = (8\omega_2^2 \omega_3 - 4\omega_2^2 + 2\omega_2^3 - 2\omega_2^3 \omega_3 - \omega_2^2 \omega_3^2 + 2\omega_3^2 - \omega_2 \omega_3^2 - 4\omega_2 \omega_3) \frac{\rho v_1}{2\omega_2^3 \omega_3^2}$$

$$C_{D_t^2 D_x^2 v_1}^{(0), \text{CLBM}^1} = (-2 - \omega_2^2 + 3\omega_2) \frac{3\rho v_1}{2\omega_2^3}$$

coefficient $C_{D_t D_x^3 v_1}^{(0)}$ **at** $\frac{\partial^4 v_1}{\partial t \partial x_1^3}$:

$$C_{D_t D_x^3 v_1}^{(0), \text{SRT}} = (-36 + 72v_1^2 + 54\omega + 34\omega^2 c_s^2 - 20\omega^2 - 2\omega^3 c_s^2 - 108\omega v_1^2 + \omega^3 + 42\omega^2 v_1^2 + 60c_s^2 - 3\omega^3 v_1^2 - 90\omega c_s^2) \frac{\rho}{12\omega^3}$$

$$C_{D_t D_x^3 v_1}^{(0), \text{MRT}^1} = (9\omega_2^3 \omega_3 c_s^2 + 36\omega_2^2 \omega_3 + 12\omega_2^2 v_1^2 - 12\omega_2^2 - 60\omega_2^2 \omega_3 v_1^2 + 6\omega_2^3 - 42\omega_2 \omega_3^2 v_1^2 + \omega_2^3 \omega_3^2 - 6\omega_2^3 v_1^2 - 9\omega_2^3 \omega_3 - 3\omega_2^3 \omega_3^2 v_1^2 + 25\omega_2^2 \omega_3^2 c_s^2 - 11\omega_2^2 \omega_3^2 + 24\omega_3^2 c_s^2 + 24\omega_2 \omega_3 c_s^2 + 12\omega_2 \omega_3^2 - 48\omega_2 \omega_3^2 c_s^2 + 15\omega_2^2 \omega_3 v_1^2 - 36\omega_2^2 \omega_3 c_s^2 + 12\omega_2^2 c_s^2 + 48\omega_2 \omega_3 v_1^2 + 12\omega_3^2 v_1^2 - 2\omega_2^3 \omega_3^2 c_s^2 - 6\omega_2^3 c_s^2 - 24\omega_2 \omega_3 + 27\omega_2^2 \omega_3^2 v_1^2) \frac{\rho}{12\omega_2^3 \omega_3^2}$$

$$C_{D_t D_x^3 v_1}^{(0), \text{CLBM}^1} = (9\omega_2^3 \omega_3 c_s^2 + 36\omega_2^2 \omega_3 + 36\omega_2^2 v_1^2 - 12\omega_2^2 - 108\omega_2^2 \omega_3 v_1^2 + 6\omega_2^3 + 18\omega_2 \omega_3^2 v_1^2 + \omega_2^3 \omega_3^2 - 18\omega_2^3 v_1^2 - 9\omega_2^3 \omega_3 - 3\omega_2^3 \omega_3^2 v_1^2 + 25\omega_2^2 \omega_3^2 c_s^2 - 11\omega_2^2 \omega_3^2 + 24\omega_3^2 c_s^2 + 24\omega_2 \omega_3 c_s^2 + 12\omega_2 \omega_3^2 - 48\omega_2 \omega_3^2 c_s^2 + 27\omega_2^2 \omega_3 v_1^2 - 36\omega_2^2 \omega_3 c_s^2 + 12\omega_2^2 c_s^2 + 72\omega_2 \omega_3 v_1^2 - 36\omega_2^3 v_1^2 - 2\omega_2^3 \omega_3^2 c_s^2 - 6\omega_2^3 c_s^2 - 24\omega_2 \omega_3 + 15\omega_2^2 \omega_3^2 v_1^2) \frac{\rho}{12\omega_2^3 \omega_3^2}$$

coefficient $C_{D_x^4 \rho}^{(0)}$ **at** $\frac{\partial^4 \rho}{\partial x_1^4}$:

$$C_{D_x^4 \rho}^{(0), \text{SRT}} = (6\omega^3 v_1^2 c_s^2 - 72\omega c_s^4 + 72v_1^2 + 3\omega^3 v_1^4 - 14\omega^2 c_s^2 - 42\omega^2 v_1^4 + \omega^3 c_s^2 - 108\omega v_1^2 + 48c_s^4 + 216\omega v_1^2 c_s^2 - 144v_1^2 c_s^2 + 42\omega^2 v_1^2 - 24c_s^2 + 108\omega v_1^4 - 3\omega^3 c_s^4 - 84\omega^2 v_1^2 c_s^2 - 3\omega^3 v_1^2 - 72v_1^4 + 36\omega c_s^2 + 30\omega^2 c_s^4) \frac{1}{24\omega^3}$$

$$C_{D_x^4 \rho}^{(0), \text{MRT1}} = (12\omega_2^3 v_1^2 c_s^2 - 48\omega_2 \omega_3 v_1^4 + 6\omega_2^3 \omega_3^2 v_1^2 c_s^2 - 6\omega_2^3 \omega_3 c_s^2 + 24\omega_2^2 v_1^2 - 72\omega_2^2 \omega_3 v_1^2 - 24\omega_2^2 \omega_3^2 v_1^4 - 96\omega_2^3 v_1^2 c_s^2 - 3\omega_2^3 \omega_3^2 c_s^4 - 24\omega_2 \omega_3^2 v_1^2 - 24\omega_2 \omega_3 v_1^2 c_s^2 - 48\omega_2 \omega_3^2 c_s^4 - 12\omega_2^3 v_1^2 - 3\omega_2^3 \omega_3^2 v_1^2 - 8\omega_2^2 \omega_3^2 c_s^2 - 24\omega_2^2 \omega_3 c_s^4 - 72\omega_2^2 \omega_3^2 v_1^2 c_s^2 - 18\omega_2^3 \omega_3 v_1^4 - 24\omega_2 \omega_3 c_s^2 + 24\omega_2^2 \omega_3^2 c_s^4 + 12\omega_2 \omega_3^2 c_s^2 + 12\omega_2^3 v_1^4 + 3\omega_2^3 \omega_3^2 v_1^4 + 48\omega_2^2 \omega_3 v_1^2 c_s^2 + 24\omega_2^2 c_s^4 + 18\omega_2^3 \omega_3 v_1^2 + 24\omega_2 \omega_3 c_s^4 + 24\omega_2^2 \omega_3 c_s^2 - 24\omega_2^2 v_1^2 c_s^2 - 24\omega_2^2 v_1^4 - 12\omega_2^3 \omega_3 v_1^2 c_s^2 + 72\omega_2^2 \omega_3 v_1^4 + 48\omega_2 \omega_3 v_1^2 + 6\omega_2^3 \omega_3 c_s^4 + \omega_2^3 \omega_3^2 c_s^2 + 24\omega_2 \omega_3^2 v_1^4 + 156\omega_2 \omega_3^2 v_1^2 c_s^2 + 24\omega_2^2 \omega_3^2 v_1^2) \frac{1}{24\omega_2^3 \omega_3^2}$$

$$C_{D_x^4 \rho}^{(0), \text{CLBM1}} = (108\omega_2^3 v_1^2 c_s^2 + 6\omega_2^3 \omega_3^2 v_1^2 c_s^2 - 6\omega_2^3 \omega_3 c_s^2 + 72\omega_2^2 v_1^2 - 72\omega_2^2 \omega_3 v_1^2 - 12\omega_2^2 \omega_3^2 v_1^4 - 3\omega_2^3 \omega_3^2 c_s^4 + 72\omega_2 \omega_3 v_1^2 c_s^2 - 48\omega_2 \omega_3^2 c_s^4 - 36\omega_2^3 v_1^2 - 3\omega_2^3 \omega_3^2 v_1^2 - 8\omega_2^2 \omega_3^2 c_s^2 - 24\omega_2^2 \omega_3 c_s^4 - 12\omega_2^2 \omega_3^2 v_1^2 c_s^2 - 30\omega_2^3 \omega_3 v_1^4 - 24\omega_2 \omega_3 c_s^2 + 24\omega_2^2 \omega_3^2 c_s^4 + 12\omega_2 \omega_3^2 c_s^2 + 36\omega_2^3 v_1^4 + 3\omega_2^3 \omega_3^2 v_1^4 + 144\omega_2^2 \omega_3 v_1^2 c_s^2 + 24\omega_2^2 c_s^4 + 30\omega_2^3 \omega_3 v_1^2 + 24\omega_2 \omega_3 c_s^4 + 24\omega_2^2 \omega_3 c_s^2 - 216\omega_2^2 v_1^2 c_s^2 - 72\omega_2^2 v_1^4 - 72\omega_2^3 \omega_3 v_1^2 c_s^2 + 72\omega_2^2 \omega_3 v_1^4 + 6\omega_2^3 \omega_3 c_s^4 + \omega_2^3 \omega_3^2 c_s^2 - 36\omega_2 \omega_3^2 v_1^2 c_s^2 + 12\omega_2^2 \omega_3^2 v_1^2) \frac{1}{24\omega_2^3 \omega_3^2}$$

coefficient $C_{D_x^4 v_1}^{(0)}$ **at** $\frac{\partial^4 v_1}{\partial x_1^4}$:

$$C_{D_x^4 v_1}^{(0), \text{SRT}} = (24 - 36v_1^2 - 36\omega - 26\omega^2 c_s^2 + 14\omega^2 + \omega^3 c_s^2 + 54\omega v_1^2 - \omega^3 - 22\omega^2 v_1^2 - 48c_s^2 + 2\omega^3 v_1^2 + 72\omega c_s^2) \frac{\rho v_1}{12\omega^3}$$

$$C_{D_x^4 v_1}^{(0), \text{MRT1}} = (-6\omega_2^3 \omega_3 c_s^2 - 24\omega_2^2 \omega_3 - 12\omega_2^2 v_1^2 + 12\omega_2^2 + 24\omega_2^2 \omega_3 v_1^2 - 6\omega_2^3 + 24\omega_2 \omega_3^2 v_1^2 - \omega_2^3 \omega_3^2 + 6\omega_2^3 v_1^2 + 6\omega_2^3 \omega_3 + 2\omega_2^3 \omega_3^2 v_1^2 - 20\omega_2^2 \omega_3^2 c_s^2 + 8\omega_2^2 \omega_3^2 - 24\omega_2^2 c_s^2 - 12\omega_2 \omega_3 c_s^2 - 6\omega_2 \omega_3^2 + 42\omega_2 \omega_3^2 c_s^2 - 6\omega_2^3 \omega_3 v_1^2 + 24\omega_2^2 \omega_3 c_s^2 - 12\omega_2^2 c_s^2 - 12\omega_2 \omega_3 v_1^2 - 12\omega_2^2 v_1^2 + \omega_2^3 \omega_3^2 c_s^2 + 6\omega_2^3 c_s^2 + 12\omega_2 \omega_3 - 16\omega_2^2 \omega_3^2 v_1^2) \frac{\rho v_1}{12\omega_2^3 \omega_3^2}$$

$$C_{D_x^4 v_1}^{(0), \text{CLBM1}} = (-24\omega_2^3 \omega_3 c_s^2 - 24\omega_2^2 \omega_3 - 84\omega_2^2 v_1^2 + 36\omega_2^2 + 24\omega_2^2 \omega_3 v_1^2 - 18\omega_2^3 - 12\omega_2 \omega_3^2 v_1^2 - \omega_2^3 \omega_3^2 + 42\omega_2^3 v_1^2 + 12\omega_2^3 \omega_3 + 2\omega_2^3 \omega_3^2 v_1^2 - 2\omega_2^2 \omega_3^2 c_s^2 + 2\omega_2^2 \omega_3^2 + 24\omega_2^2 c_s^2 - 12\omega_2 \omega_3 c_s^2 + 6\omega_2 \omega_3^2 + 30\omega_2 \omega_3^2 c_s^2 - 24\omega_2^3 \omega_3 v_1^2 + 72\omega_2^2 \omega_3 c_s^2 - 60\omega_2^2 c_s^2 + 60\omega_2 \omega_3 v_1^2 - 12\omega_2^3 v_1^2 + \omega_2^3 \omega_3^2 c_s^2 + 30\omega_2^3 c_s^2 - 12\omega_2 \omega_3 + 2\omega_2^2 \omega_3^2 v_1^2) \frac{\rho v_1}{12\omega_2^3 \omega_3^2}$$

References

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